

# On equations of Korteweg–de Vries type with highest symmetry properties

*H. LAHNO* †, *V. SMALIJ* ‡

† *Poltava State Pedagogical University*

*E-mail: laggo@poltava.bank.gov.ua*

‡ *National Agrarian University, Kyiv*

Представлено результати групової класифікації одного класу нелінійних еволюційних рівнянь третього порядку, що допускають чотирьохвимірні алгебри Лі операторів симетрії.

We present results on group classification of one class of third-order nonlinear evolution equations admitting four-dimensional solvable Lie algebras of symmetry operators.

The standard Korteweg–de Vries equation  $u_t = u_{xxx} + uu_x$  belongs to the family of evolution equations

$$u_t = u_{xxx} + F(t, x, u, u_x, u_{xx}), \quad (1)$$

where  $u = u(t, x)$ ,  $u_t = \frac{\partial u}{\partial t}$ ,  $u_x = \frac{\partial u}{\partial x}$ ,  $u_{xx} = \frac{\partial^2 u}{\partial x^2}$ ,  $u_{xxx} = \frac{\partial^3 u}{\partial x^3}$ .

The problem of group classification of equation (1) was solved by F. Güngör, V. Lahno and R. Zhdanov [1]. But their result of group classification is not complete. They obtained all classes of nonlinear equations of the form (1) that admit one-, two-, three- and four-dimensional solvable Lie algebras.

Here we investigate the symmetry properties of nonlinear equations of the form (1) whose invariance algebras are isomorphic to solvable Lie algebras  $2A_{2.2} = \langle e_1, e_2 \rangle \oplus \langle e_3, e_4 \rangle$  ( $[e_1, e_2] = e_2$ ,  $[e_3, e_4] = e_4$ ),  $A_{2.2} \oplus 2A_1 = \langle e_1, e_2 \rangle \oplus \langle e_3 \rangle \oplus \langle e_4 \rangle$  ( $[e_1, e_2] = e_2$ ) and  $A_{3.3} \oplus A_1 = \langle e_1, e_2, e_3 \rangle \oplus \langle e_4 \rangle$  ( $[e_2, e_3] = e_1$ ,  $[e_1, e_2] = [e_1, e_3] = 0$ ).

According to [1] the complete list of such equations contains following nine equations:

$$1) \quad u_t = u_{xxx} + u_x^3 - 3u_x u_{xx} + x^{-2} u_x \tilde{F}(\omega),$$

- $$\omega = x(u_x^{-1}u_{xx} - u_x);$$
- 2)  $u_t = u_{xxx} + \frac{\lambda}{3t}\omega_1 \ln|\omega_1| + \frac{\omega_1}{t}\tilde{F}(\omega), \quad \omega_1 = t^{\frac{1}{3}}u_x,$   
 $\omega = t^{\frac{1}{3}}u_x^{-1}u_{xx}, \quad \lambda \in \mathbb{R};$
  - 3)  $u_t = u_{xxx} - \lambda xu_x - \lambda u_x \ln|u_x| + u_x\tilde{F}(\omega),$   
 $\omega = u_x^{-1}u_{xx}, \quad \lambda \neq 0;$
  - 4)  $u_t = u_{xxx} - (1 + \lambda^{-1})u_x + e^{-x}\tilde{F}(\omega),$   
 $\omega = e^x(u_x + u_{xx}), \quad \lambda \neq 0;$
  - 5)  $u_t = u_{xxx} - \gamma^{-1}(1 + \gamma^3)u_x + e^{(\gamma - \beta^{-1})x - t}\tilde{F}(\omega),$   
 $\omega = e^{t + (\beta^{-1} - \gamma)x}(\gamma u_x - u_{xx}), \quad \gamma\beta \neq 0;$
  - 6)  $u_t = u_{xxx} - u_x + e^{-x}\tilde{F}(\omega), \quad \omega = e^x(u_x + u_{xx});$
  - 7)  $u_t = u_{xxx} + u_x\tilde{F}(\omega), \quad \omega = u_{xx}u_x^{-1};$
  - 8)  $u_t = u_{xxx} - (\lambda^3 + 1)\lambda^{-1}u_x + e^{-t + \lambda x}\tilde{F}(\omega),$   
 $\omega = e^{t - \lambda x}(\lambda u_x - u_{xx}), \quad \lambda \neq 0;$
  - 9)  $u_t = u_{xxx} + \lambda^{-1}x - \beta u_x + \tilde{F}(u_{xx}), \quad \lambda > 0, \quad \beta \in \mathbb{R}. \quad (2)$

Using the standard Lie approach we prove that the maximal invariance group of equations (1) is generated by the operator

$$v = \tau(t)\partial_t + \left(\frac{1}{3}\dot{\tau}x + \rho(t)\right)\partial_x + \eta(t, x, u)\partial_u, \quad (3)$$

where the functions  $\tau, \rho, \eta$  and  $F$  are arbitrary solutions of a single partial differential equation

$$\begin{aligned} & -3u_x\dot{\rho} - xu_x\ddot{\tau} - 9u_xu_{xx}\eta_{uu} - 3u_x^3\eta_{uuu} + 3\eta_t - 9u_{xx}\eta_{xu} - \\ & - 9u_x^2\eta_{xuu} - 9u_x\eta_{xxu} - 3\eta_{xxx} + 3(\eta_u - \dot{\tau})F + (2u_{xx}\dot{\tau} - \\ & - 3u_{xx}\eta_u - 3u_x^2\eta_{uu} - 6u_x\eta_{xu} - 3\eta_{xx})F_{u_{xx}} + (u_x\dot{\tau} - 3u_x\eta_u - \\ & - 3\eta_x)F_{u_x} - 3\eta F_u - 3\tau F_t - (3\rho + x\dot{\tau})F_x = 0. \end{aligned} \quad (4)$$

Here the dot over a symbol stands for the time derivative.

The equations (2) contain arbitrary functions of one variable. Therefore we utilize the Lie–Ovsyannikov method [2,3] of group classification of differential equations. We consider in more detail first and sixth equations (2).

In first equation (2)

$$F = u_x^3 - 3u_xu_{xx} + x^{-2}u_x\tilde{F}(\omega), \quad \omega = x(u_x^{-1}u_{xx} - u_x).$$

From the equation (4) we find that the functions  $\tau$ ,  $\rho$ ,  $\eta$  in the operator (3) and the function  $\tilde{F}$  satisfy following system of equations:

$$\begin{aligned} \eta_{uuu} - \eta_u &= 0; \\ x^{-1}[\eta_{uu} - \eta_u]\tilde{F}_\omega + 3x^{-1}[\eta_{uu} - \eta_u]\omega + 3[\eta_{xuu} - \eta_{xu}] &= 0; \\ x^{-1}[x^{-2}\rho\omega - 2\eta_x + 2\eta_{xu}]\tilde{F}_\omega - 2x^{-3}\rho\tilde{F} &= \\ &= 3x^{-1}(\eta_x - \eta_{xu})\omega + 3(\eta_{xx} - \eta_{xxu}) - \frac{1}{3}x\ddot{\tau} - \dot{\rho}; \\ [x^{-2}\eta_x\omega - x^{-1}\eta_{xx}]\tilde{F}_\omega - x^{-2}\eta_x\tilde{F} &= \eta_{xxx} - \eta_t. \end{aligned} \quad (5)$$

If  $\tilde{F}$  is arbitrary function, then from (5) we obtain that corresponding operator  $v$  has following form:

$$v = (C_1t + C_2)\partial_t + \frac{1}{3}C_1x\partial_x + C_3e^u\partial_u + C_4\partial_u,$$

where  $C_1, C_2, C_3, C_4 \in \mathbb{R}$ .

The corresponding invariance algebra is isomorphic to solvable Lie algebra  $2A_{2,2}$ :  $e_1 = -t\partial_t\frac{1}{3}x\partial_x$ ,  $e_2 = \partial_t$ ,  $e_3 = \partial_u$ ,  $e_4 = e^u\partial_u$ .

The extension of symmetry properties of first equation (2) takes place in two cases:

- (1)  $\tilde{F} = \lambda\omega^2$  ( $\lambda \neq 0, -\frac{3}{2}$ ): here  
 $\tau = C_1t + C_2$ ,  $\rho = C_3$ ,  $\eta = C_4e^u + C_5$ ,  
 $C_i \in \mathbb{R}$  ( $i = 1, 2, \dots, 5$ );
- (2)  $\tilde{F} = -\frac{3}{2}\omega^2$ : here  
 $\tau = C_1t + C_2$ ,  $\rho = C_3$ ,  $\eta = C_4e^u + C_5e^{-u} + C_6$ ,  
 $C_i \in \mathbb{R}$  ( $i = 1, 2, \dots, 6$ ).

In sixth equation (2)  $F = -u_x + e^{-x}\tilde{F}(\omega)$ ,  $\omega = e^x(u_x + u_{xx})$ ,  $\tilde{F}_{\omega\omega} \neq 0$ , and from the equation (4) we find that the functions  $\tau$ ,  $\rho$ ,  $\eta$ ,  $\tilde{F}$  satisfy following system of equations:

$$\begin{aligned} \eta_{uuu} &= 0; \quad \eta_{uu}(1 - \tilde{F}_\omega) - \eta_{xuu} = 0; \\ (\dot{\tau} + 6\eta_{xu})\tilde{F}_\omega &= -9e^{-x}\omega\eta_{uu} - 3\dot{\rho} - x\ddot{\tau} + 9\eta_{xu} - 9\eta_{xxu}; \\ [e^x(2\dot{\tau} - 3\eta_u - 3\rho - x\dot{\tau})\omega - 3\eta_x - 3\eta_{xx}]\tilde{F}_\omega &+ \\ &+ e^{-x}(3\eta_u - 3\dot{\tau} + 3\rho + x\dot{\tau})\tilde{F} - 9e^{-x}\omega\eta_{xu} + \\ &+ 3\eta_t - 3\eta_x - 3\eta_{xxx} = 0. \end{aligned} \quad (6)$$

From second equation (6) we obtain the condition

$$\eta_{uu}\tilde{F}_{\omega\omega} = 0,$$

consequently  $\eta_{uu} = 0$ .

From third equation (6) we obtain the condition

$$(\dot{\tau} + 6\eta_{xu})\tilde{F}_{\omega\omega} = 0,$$

consequently

$$\dot{\tau} + 6\eta_{xu} = 0, \quad -3\dot{\rho} - x\ddot{\tau} + 2\dot{\tau} + 9\eta_{xu} - 9\eta_{xxu} = 0.$$

From obtained relations we obtain following values of the functions  $\tau, \rho, \eta$ :

$$\begin{aligned} \tau &= C_1t + C_2, \quad \rho = \frac{1}{6}C_1t + C_3, \\ \eta &= \left[-\frac{1}{6}C_1x + \gamma(t)\right]u + \beta(t, x), \quad C_1, C_2, C_3 \in \mathbb{R}. \end{aligned}$$

Fourth equation (6) transforms into following system:

$$\begin{aligned} \frac{1}{2}C_1\tilde{F}_{\omega} &= -3\dot{\gamma} + \frac{1}{2}C_1, \\ [e^{-x} (2C_1 - \frac{1}{2}xC_1 - 3\gamma - \frac{1}{2}C_1t - 3C_3)\omega - 3\beta_x - 3\beta_{xx}] \tilde{F}_{\omega} + \\ &+ e^{-x} (-3C_1 + \frac{1}{2}xC_1 + \frac{1}{2}C_1t + 3C_3 + 3\gamma) \tilde{F} = \\ &= -\frac{3}{2}e^{-x}C_1\omega - 3\beta_t - 3\beta_x + 3\beta_{xxx}. \end{aligned} \tag{7}$$

From first equation (7) we obtain condition

$$C_1\tilde{F}_{\omega\omega} = 0,$$

consequently  $C_1 = 0, \gamma = C_4, C_4 \in \mathbb{R}$ . Second equation (7) reduces to equation

$$[(C_3 + C_4)\omega + \beta_x + \beta_{xx}]\tilde{F}_{\omega} - (C_3 + C_4)\tilde{F} = e^x(\beta_t + \beta_x - \beta_{xxx}),$$

from which we obtain condition

$$[(C_3 + C_4)\omega + \beta_x + \beta_{xx}]\tilde{F}_{\omega\omega} = 0.$$

Consequently,  $C_3 + C_4 = 0, \beta_x + \beta_{xx} = 0, \beta_t + \beta_x - \beta_{xxx} = 0$ , and the operator  $v$  (3) has following form:

$$v = C_2\partial_t + C_3\partial_x + (-C_3u + C_5 + e^{-x}C_6)\partial_u,$$

$C_2, C_3, C_4, C_5 \in \mathbb{R}$ . The corresponding invariance algebra is isomorphic to solvable Lie algebra  $A_{2,2} \oplus 2A_1$ :  $e_1 = \partial_x - u\partial_u$ ,  $e_2 = \partial_u$ ,  $e_3 = \partial_t$ ,  $e_4 = e^{-x}\partial_u$ .

So we have obtained that sixth equation (2) does not suppose the extension of symmetry properties. Analogous results we have obtained for 3, 4, 5 and 8 equations (2). The rest equations (2) suppose the extensions of symmetry properties. We give these equations with the corresponding invariance algebras:

- 1)  $u_t = u_{xxx} + u_x^3 - 3u_x u_{xx} + \lambda u_x (u_x^{-1} u_{xx} - u_x)^2, \lambda \neq 0, -\frac{3}{2} :$   
 $\langle t\partial_t + \frac{1}{3}x\partial_x, \partial_t, \partial_x, e^u\partial_u, \partial_u \rangle;$
- 2)  $u_t = u_{xxx} - \frac{3}{2}u_x^{-1}u_{xx}^2 - \frac{1}{2}u_x^3 :$   
 $\langle t\partial_t + \frac{1}{3}x\partial_x, \partial_t, \partial_x, e^u\partial_u, e^{-u}\partial_u, \partial_u \rangle;$
- 3)  $u_t = u_{xxx} + \lambda^{-1}x + m \ln |u_{xx}| - \beta u_x, \lambda \cdot m \neq 0, \beta \in \mathbb{R} :$   
 $\langle t\partial_t + (\frac{1}{3}x + \frac{2}{3}\beta t)\partial_x + [u + \frac{1}{3}t(\lambda^{-1}x + \frac{1}{2}\beta\lambda^{-1}t + m)]\partial_u,$   
 $\partial_x + \lambda^{-1}t\partial_u, (x - \beta t)\partial_u, \partial_t, \partial_u \rangle;$
- 4)  $u_t = u_{xxx} + \lambda^{-1}x - \beta u_x + m|u_{xx}|^p, \lambda m \neq 0, p \neq 0, 1, \beta \in \mathbb{R} :$   
 $\langle t\partial_t + (\frac{1}{3}x + \frac{2}{3}\beta t)\partial_x + \left[ \frac{2p-3}{3(p-1)}u + \frac{2p-1}{3\lambda(p-1)}tx + \right.$   
 $\left. + \frac{\beta}{6\lambda(1-p)}t^2 \right] \partial_u, \partial_x + \lambda^{-1}t\partial_u, (x - \beta t)\partial_u, \partial_t, \partial_u \rangle;$
- 5)  $u_t = u_{xxx} + \lambda^{-1}x - \beta u_x + me^{nu_{xx}}, \lambda mn \neq 0, \beta \in \mathbb{R} :$   
 $\langle t\partial_t + (\frac{1}{3}x + \frac{2}{3}\beta t)\partial_x + \left[ \frac{2}{3}u + \frac{1}{6n}x^2 + \left( \frac{2}{3\lambda} - \frac{\beta}{3n} \right)tx + \right.$   
 $\left. + \frac{\beta^2}{6n}t^2 \right] \partial_u, \partial_x + \lambda^{-1}t\partial_u, (x - \beta t)\partial_u, \partial_t, \partial_u \rangle.$

- [1] Güngör F., Lahno V., Zhdanov R. Symmetry classification of KdV-type nonlinear evolution equations // J. Math. Phys. – 2004. – **45**. – P. 2280–2113.
- [2] Ovsyannikov L.V. Group analysis of differential equations. – New York: Academic, 1982.
- [3] Olver P.J. Applications of Lie groups to differential equations. – New York: Springer-Verlag, 1986.